5.13

We do not include the gravitational force Mg in the free-body diagram for the mass, because displacements are measured from the static equilibrium condition caused by gravity. Note that the free-body diagram for the lever is labeled with torques. From (5), we obtain

$$J_A = \frac{M}{3L} \left[\left(\frac{L}{4} \right)^3 + \left(\frac{3L}{4} \right)^3 \right] = \frac{7ML^2}{48}$$

In drawing the diagrams, we used $x_2 = (L/4)\theta$, $x_3 = (3L/4)\theta$, and $v_3 = (3L/4)\omega$ Summing the forces on the mass and summing the torques about the lever's pivot point, we have

$$\begin{split} M\dot{v}_1 + B_1v_1 + (K_1 + K_2)x_1 - \frac{LK_2}{4}\theta &= 0\\ \frac{7ML^2}{48}\dot{\omega} + \frac{9L^2B_2}{16}\omega + \frac{L^2K_2}{16}\theta - \frac{LK_2}{4}x_1 + \frac{3L}{4}f_a(t) &= 0 \end{split}$$

We select x_1 , v_1 , θ , and ω as the state variables and write

$$\dot{x} = v$$

$$\dot{v} = \frac{1}{M} \left[-(K_1 + K_2)x_1 - B_1v_1 + \frac{LK_2}{4}\theta \right]$$

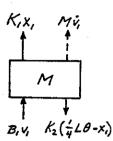
$$\dot{\theta} = \omega$$

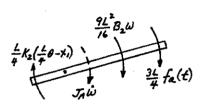
$$\dot{\omega} = \frac{3}{7ML} \left[4K_2x_1 - LK_2\theta - 9LB_2\omega - 12f_a(t) \right]$$

$$\frac{L}{4} K_2 \left(\frac{L}{4}\theta - \frac{L}{4} \right)$$

The output equation is

$$f_{K_2} = -K_2 x + \frac{LK_2}{4} \theta$$





6.9

Let e_A denote the node voltage at the top of the inductor, and i_L the current down through the inductor Applying Kirchhoff's current law to nodes A and O gives

$$-i_{i}(t) + i_{I}(0) + \frac{1}{8} \int_{0}^{t} e_{A} d\lambda + \frac{1}{4} (e_{A} - e_{o}) = 0$$
 (A)

 $\frac{1}{4}(e_o - e_A) + \frac{1}{2}\dot{e}_o + \frac{1}{4}e_o = 0$ (B)

Differentiating (A) and simplifying both equations, we obtain

$$\begin{aligned} 2\dot{e}_A + e_A - 2\dot{e}_o &= 8\frac{di_i}{dt} \\ e_A &= 2\dot{e}_o + 2e_o \end{aligned} \tag{C}$$

$$e_A = 2\dot{e}_o + 2e_o \tag{D}$$

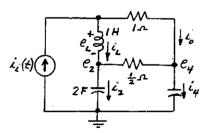
Substituting (D) into (C), we get

$$\ddot{e}_{g} + \dot{e}_{o} + \frac{1}{2}e_{o} = 2\frac{di_{i}}{dt}$$

6.25

We choose e_2, e_4 , and i_L as the state variables. The output equation is $i_o = i_i(t) - i_L$ Summing the currents leaving node 2, the currents leaving node 4, and the voltages around a closed path that contains the inductor and the capacitors, we have

$$\begin{array}{rcl} i_2 + 2(e_2 - e_4) - i_L & = & 0 \\ i_4 + 2(e_4 - e_2) - [i_i(t) - i_L] & = & 0 \\ e_2 + e_L - e_4 - [i_i(t) - i_L] & = & 0 \end{array}$$



We solve these equations for i_2, i_4 , and e_2 and then use the element laws $\dot{e}_2 = 0.5i_2, \dot{e}_4 = 0.25i_4$, and $di_L/dt = e_L$ in order to get the state-variable equations

$$\begin{array}{rcl} \dot{e}_2 & = & -e_2 + e_4 + \frac{1}{2}i_I \\ \dot{e}_4 & = & \frac{1}{2}e_2 - \frac{1}{2}e_4 - \frac{1}{4}i_I + \frac{1}{4}i_i(t) \\ \frac{di_L}{dt} & = & -e_2 + e_4 - i_I + i_i(t) \end{array}$$

6.30

(a) Because $i_A + i_B = i_i(t)$, we have only one state variable, which we initially choose to be i_A . By Kirchhoff's voltage law,

$$L_1 \frac{di_A}{dt} + R_1 i_A = L_2 \frac{di_B}{dt} + R_2 \dot{j}_B$$

Replacing i_B by $i_i(t) - i_A$ gives

$$(L_1 + L_2)\frac{di_A}{dt} + (R_1 + R_2)i_A = L_2\frac{di_i}{dt} + R_2i_i(t)$$

Defining the new state variable

$$x = (L_1 + L_2)i_A - L_2i_i(t)$$

we get

$$\dot{x} = -\left(\frac{R_1 + R_2}{L_1 + L_2}\right)x + \left(\frac{R_2L_1 - R_1L_2}{L_1 + L_2}\right)i_i(t)$$

where

$$i_A = \frac{1}{L_1 + L_2} [x + L_2 i_i(t)]$$

(b) The output voltage e_o is given by

$$e_o = L_1 \frac{di_A}{dt} + R_1 i_A = \frac{1}{L_1 + L_2} \left[L_1 \dot{x} + L_1 L_2 \frac{di_i}{dt} + R_1 x + R_1 L_2 i_i(t) \right]$$

Inserting the expression for \dot{x} and simplifying the result, we find that

$$e_o = \frac{1}{(L_1 + L_2)^2} \left[(R_1 L_2 - R_2 L_1) q + L_1 L_2 (L_1 + L_2) \frac{di_i}{dt} + (R_2 L_1^2 + R_1 L_2^2) i_i(t) \right]$$

In this situation, we cannot avoid a derivative of the input on the right side of the output equation

6.33

Let e_A and e_B denote the voltages at the inverting and noninverting terminals, respectively, of the op-amp. Summing the currents leaving node A gives

$$\frac{1}{R_1}e_A + \frac{1}{R_2}(e_A - e_o) + C(\dot{e}_A - \dot{e}_o) = 0 \tag{A}$$

Because no current enters the input terminals of the op-amp, we use the voltage-divider rule to write

$$e_B = \frac{R_4}{R_3 + R_4} e_i(t) \tag{B}$$

By the virtual-short concept, $e_B=e_A$ Using this fact, we substitute (B) into (A) to obtain

$$C\dot{e}_o + rac{1}{R_2}e_o = rac{R_4}{R_3 + R_4} \left[C\dot{e}_i + rac{R_1 + R_2}{R_1 R_2}e_i(t)
ight]$$